Sino-German Workshop

Dynamic Maps



2009.12.07 - 2009.12.09

At the

Haiyi Jinjiang Hotel

海怡锦江大酒店



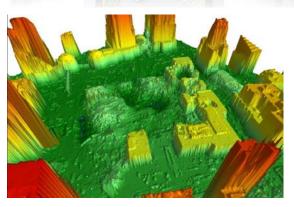
Organized by



Wuhan University

AND







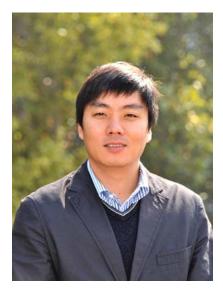
Leibniz University Hannover

Supported by



Organizer (in China)

Bisheng Yang



Bisheng Yang obtained his Ph.D degree in Photogrammetry and Remote Sensing from Wuhan University, China in 2002. He was a Post-doctoral Research Fellow in GIS Division, Department of Geography, University of Zurich, Switzerland from October 2002 to October 2006. He is now a Full Professor at the State Key Laboratory of Information Engineering in Surveying, Mapping and Remote Sensing (LIESMARS) in Wuhan University. His research interests cover multi-resolution data modelling, laser point clouds processing, 2D/3D visualization, progressive transmission of spatial data over the Internet.

Organizer (in Germany)

Claus Brenner



Claus Brenner received his diploma in computer science in 1994 and his PhD (Dr.-Ing.) from the faculty of civil engineering and surveying in 2000, both from the University of Stuttgart, Germany. From 1994 to 2000, he was with the Institute for Photogrammetry, University of Stuttgart, from 1996 on as head of the optical inspection group. From 2000 to 2002, he worked for Robert Bosch Corporate Research and Development, investigating next generation car navigation systems. Since 2002 he is with the Institute of Cartography and Geoinformatics, where he leads a junior research group on 'Automatic methods for the fusion, reduction and

consistent combination of complex heterogeneous geoinformation'. His research interests are automated object extraction from images and laser scanning data, as well as modeling and generalization.

Brief Introduction

Future mapping will replace the traditional separation between map making and map usage by a holistic approach, where participants, equipped with sensors, use map data while at the same time contribute information, effectively keeping the map up to date at all times. This workshop brings together experts from the classical mapping community – photogrammetry, geodesy, geoinformatics, and cartography – and experts from related fields, such as computer vision, computer graphics, robotics, machine learning and autonomous driving.

It is our common goal to pursue research towards new mapping approaches, focusing on topics such as:

- new platforms for low-altitude and close range acquisition, e.g. unmanned airships and micro drones
- highly detailed modeling of large scenes and structures
- capture, mapping, perception, and localization in dynamic scenes
- automotive and robotic mapping
- representation and visualization of dynamic scenes
- persistent localization and mapping
- interrelation of mapping and driver assistance / autonomous driving
- data models and structures for dynamic maps
- high-performance retrieval of (high-dimensional) spatial information
- integration of multiple sensors like airborne, terrestrial, and mobile platform sensors, including 'consumer grade' sensors
- interpretation and fusion aspects applied to acquisition
 'systems of systems' of inhomogeneous resolution and accuracy
- geo-sensor networks to collect spatiotemporal data
- detailed capture of cultural heritage objects
- aspects of pattern recognition, especially recognition and modeling of complex 3D structures.

It is a major purpose of the workshop to look at the dynamic mapping problem from the viewpoints of different disciplines and arrive at a more concrete definition of research projects which are properly mirrored between the Chinese and German partners.

	Ma	onday, December 7, 2009			
8.30~9.00	Opening Ceremony				
9:00-9:15	Photo				
9.15~10.45	3D Mapping				
	Digital Cultural H	eritage in China (45 minutes)		Deren Li	
	Future maps and	mapping infrastructures	(Claus Brenner	
	Topographic Mapping with High-resolution optical remote sensing imagery in remote areas		Li Zhang		
	6D SLAM – Small and Large Scale Robotic 3D		D	Andreas	
	Mapping			Nuechter	
10:45~11:00	Coffee & Tea Break				
	Modeling				
11:00~12:15	World modeling	World modeling		Giorgio Grisetti	
	Level-of-detail Modeling from Laser Scanning Point Clouds			Bisheng Yang	
	• •	fusion of multi-sensor for dynamic site model genera	and tion	Stefan Hinz	
	Multi-scale Modeling		Zhilin Li		
	Machine learning of models (grammars) for high resolution models of historical buildings		Lutz Plümer		
12:15~13:45		ů – Elektrik			
12:15~13:45		Lunch Break			
12:15~13:45		Lunch Break Robotic mapping	ns	Sven Behnke	
	Hierarchical Strue	Lunch Break		Sven Behnke Qingquan Li	
12:15~13:45 14:00~15:00	Hierarchical Struc	Lunch Break Robotic mapping cture in Spatial Representation ption Modeling for Autonomou			
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14:00~15:00	Hierarchical Struc Dynamical Perce Driving Dynamic pattern Annotation of	Lunch Break Robotic mapping cture in Spatial Representation ption Modeling for Autonomou recognition Geographical Information i	in	Qingquan Li Wolfgang Förstner	
14:00~15:00	Hierarchical Struc Dynamical Perce Driving Dynamic pattern Annotation of	Lunch Break Robotic mapping cture in Spatial Representation ption Modeling for Autonomou recognition Geographical Information is e Coffee & Tea Break	in	Qingquan Li Wolfgang Förstner	
14:00~15:00 15:00~15:15	Hierarchical Struc Dynamical Perce Driving Dynamic pattern Annotation of Natural Language	Lunch Break Robotic mapping cture in Spatial Representation ption Modeling for Autonomou recognition Geographical Information is Coffee & Tea Break Group 1.	in	Qingquan Li Wolfgang Förstner	
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14:00~15:00 15:00~15:15 15:15~16:45	Hierarchical Struct Dynamical Perce Driving Dynamic pattern Annotation of Natural Language Discussion Incremental Map Towards an Om Large Dynamic E Towards Automat Understanding Us	Lunch Break Robotic mapping cture in Spatial Representation ption Modeling for Autonomou recognition Geographical Information is Coffee & Tea Break Group 1. Group 2. Group 3. ping ni-Directional Measurement of nvironment tic Mapping and Dynamic 3D Solution	in y	Qingquan Li Wolfgang Förstner Kueying Zhang Jukka Krisp Huijing Zhao	
14:00~15:00 15:00~15:15 15:15~16:45	Hierarchical Struct Dynamical Perce Driving Dynamic pattern Annotation of Natural Language Discussion Incremental Map Towards an Om Large Dynamic E Towards Automat Understanding Us	Lunch Break Robotic mapping cture in Spatial Representation ption Modeling for Autonomou recognition Geographical Information is Coffee & Tea Break Group 1. Group 2. ping ni-Directional Measurement of nvironment tic Mapping and Dynamic 3D So sing Camera-Based Systems	in y	Qingquan Li Wolfgang Förstner Kueying Zhang Jukka Krisp Huijing Zhao Olaf Hellwich	

	Tue	esday, December 8, 2009			
		Data Acquisition and Processing			
9:00~10:15	Digitizing of E-heritage Using Terrestrial Laser			min Wang	
	Similarity and Self-Similarity in Geometry Acquisition			Andreas Schilling	
	Spatial Data for Rapid Response of Emergency			Jing Li	
				nika Sester	
	· · · · · · · · · · · · · · · · · · ·			ioan Tang	
10:15~10:30		Coffee & Tea Break			
		Data Acquisition and Processing			
	3D Reconstruction	n and Object Extraction from UAV	and	Helmut	
	Terrestrial Image	Sequences		Mayer	
	Complex Primitive	e Segmentation from Terrestrial P	oint	Zhizhong	
	Clouds based on	Panoramic Reflectance Images		Kang	
10:30~11:45	Feature Extraction	n by Meanshift Method from Airbo	orne		
	LIDAR Data Fuse	d with Aerial-Image		Chun Liu	
	Challenges in enr	Challenges in enrichment and automatic texturing of			
	3d building mode	ls by terrestrial and airborne IR vi	ideo	Uwe Stilla	
	Automatic Extraction of Building Footprints from				
	Airborne LIDAR D	pata		Zhi Wang	
11:45-12:00	Short Summary				
12:15~13:45		Lunch Break			
	Applications				
	3D Data Modeling	g of Ming Great Wall		Jun Chen	
14.00 15.00	Small Stack PS-InSAR in Shanghai			Mingsheng Liao	
14:00~15:00	Photogrammetric data acquisition for dynamic maps using image sequences			Christian Heipke	
	Monitoring and Precaution of dangerous moving			Lixin Wu	
	objects in disaste				
15:00~15:15	Coffee & Tea Break				
15:15~16:30	Discussion	Group 1.			
13.15-10.50	Discussion	Group 2.			
16:30~17:15	Digital Photogrammetric Grid and Applications in Fast		Fast	Yongjun	
	Processing of Aerial and Low Altitude Images			Zhang	
	3D Mapping for Mobiles			Christoph Stiller	
	Multi-Data Source based e-Heritage			Xianfeng Huang	
18:00~		Dinner			

Wednesday, December 9, 2009						
9:00~11:00	Discussion	Final discussion, first steps towards proposals.				
11:00~12:00	Technical Visit	Tour to State Key Laboratory of Information Engineering in Surveying, Mapping and Remote Sensing				
12:00~14:00		Lunch Break				
14:00~17:00	Technical Visit	Tour to Wuhan Wuda Zoyon Science and Technology Co., Ltd., Wuhan Wuda Geoinformatics Co., Ltd.				
17:30~	Dinner					

	Speaker	Institute		Speaker	Institute
Germany	Sven Behnke	Universität Bonn		Bisheng Yang	Wuhan University
	Claus Brenner	Universität Hannover		Jun Chen	NFGIS
	Giorgio Grisetti	Universität Freiburg		Qingquan Li	Wuhan University
	Wolfgang Förstner	Universität Bonn		Deren Li	Wuhan University
	Christian Heipke	Universität Hannover			
	Olaf Hellwich	Technische Universität Berlin		Yanmin Wang	Beijing University of Civil Engineering and Architecture
	Stefan Hinz	Universität Karlsruhe	China	Xueying Zhang	Nanjing Normal University
	Helmut Mayer	Universität der Bundeswehr München		Li Zhang	Chinese Academy of Surveying & Mapping
	Jukka Krisp	Technische Universität München		Mingsheng Liao	Wuhan University
	Andreas Nuechter	Jacobs University Bremen		Zhizhong Kang	China University of Geosciences
	Lutz Plümer	Universität Bonn		Zhilin Li	Hong Kong Polytechnic University
	Andreas Schilling	Universität Tübingen		Huijing Zhao	Peking University
	Monika Sester	Universität Hannover		Shuming Tang	Chinese Academy of Sciences
	Uwe Stilla	Technische Universität München		Guoan Tang	Nanjing Normal University
	Christoph Stiller	Universität Karlsruhe		Jing Li	Beijing Normal University
				Yongjun Zhang	Wuhan University
			Ē	Chun Liu	Tongji University
				Lixin Wu	Beijing Normal University
				Xianfeng Huang	Wuhan University
				Zhi Wang	Northeastern University

The workshop will be held at the Haiyi Jinjiang Hotel

海怡锦江大酒店

湖北武汉市武昌洪山路特1号武汉电信商务会议中心

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